Making the Next Generation of 3D Interstellar Medium Dust Temperature Maps

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- Characterizing the Interstellar Radiation field
- Investigating gamma-ray diffused emission for dark matter annihilation surveys.
- \Box It does this by modelling the dust emission as a single modified blackbody; the total dust emission (I_{ν}) from each 2D pixel is a function of cumulating 3D reddening (ΔE_{B-V}) in each distance bin along the line-of-sight.

$I_{\nu}^{\mathrm{total},k} = O_{\nu} + \sum_{\omega} \zeta_{353}^n \Delta E_{\mathrm{B\text{-}V}}^{n,k} \big(\frac{\nu}{\nu_0}\big)^{\beta^n} B_{\nu}(T^n) \ ,$

 \Box The parameters of this model ζ_{353}^n , β^n and T^n are obtained using Bayesian

Fig 1: Brief description of how dust clouds interact

transmission

Dust
cloud

 $\begin{array}{c}\n\hline\n\text{Bhuc} \\
\text{reflection}\n\end{array}$

with light All these applications significantly benefit from increasing angular resolution of the temperature map as much as possible

Inference, with temperature $T^{\bm n}$ allowed to vary along the line of sight.

- Stage 1: All the data pixels are rotated by the same Euler angle $[\alpha_i,\beta_i].$ This is repeated for several calculated rotation angles that give unique groupings.
- ❑ Stage 2: Data pixels are grouped into larger pixels called 'superpixels' (in blue). Note that the same superpixel contains different data points for each rotated map.
- Stage 3: Each pair of datasets (emission and reddening) is loaded into the optimiser, which carries out the Bayesian inference to obtain the Temperature \Box values for each superpixel at each distance slice. Notice that there is one temperature value per superpixel, thus these maps are lower resolution.

Methods: How do we Utilize Different Tessellations of the Sky to Create New Versions of the Temperature Map?

STAGES SUMMARIZED

- ❑ Stage 0: Start with dust emission datasets and dust reddening datasets smoothed to matching 5' resolutions (Smoothed HEALPix Nside 1024)
- ❑ Stage 4: For the rotated maps, we carry out the inverse rotation on the coordinates of the temperature superpixels, to account for the initial rotation. For each new map, we collect the new latitude θ and longitude ϕ and temperature T values for each superpixel. Stage 5: At each distance slice, the coordinates and corresponding temperature values are inserted into an R* Tree spatial unstructured grid. Temperature values are inferred in between known points by interpolating with a kriging covariance function or a window function. Stage 6: By sampling temperature values at the desired coordinates for a higher resolution map, the new map is constructed.

UNCERTAINTIES AND LIMITATIONS

❑ Uncertainties in rotations: The HEALPix pixelization of the sky is not always evenly spaced in latitude, thus rotations across latitudes are not exact everywhere

on the map. This is further affected by uneven distributions of neighbouring pixels in polar regions.

❑ Uncertainties in Interpolations: Interpolations between known data coordinates are always estimates based on weights and distances between a chosen number of neighbours.

Results: New 3D Temperature Maps with 4 times Improved Resolution!! & &

The current temperature map achieved only 27' angular resolution (from 5' data) because original data pixels need to be grouped into 'superpixels' to be able to infer temperature along the line of sight